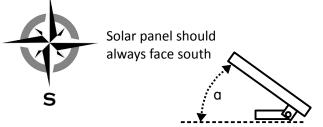
# ECOSOL/LIBRA UL-R



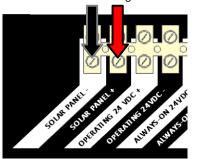
The angle of the panel  $(\alpha)$  should equal the locations latitude ≤ 10°

i.e.: Dallas,  $TX = 33^{\circ}-43^{\circ}$ ; Houston,  $TX = 30^{\circ}-40^{\circ}$ ; Phoenix AZ = 33.5°-43.5°; San Juan, PR = 18°-28°

#### **SOLAR PANEL INSTALLATION**

Connect the wires to the terminals labeled "Solar Panel". Cable should not exceed 15 ft (16AWG minimum). POLARITY MUST BE RESPECTED.

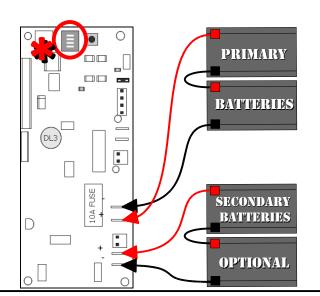
Check before connecting



#### **BATTERY CONNECTIONS**



Dip-switch #1 must be turned on when secondary batteries are connected



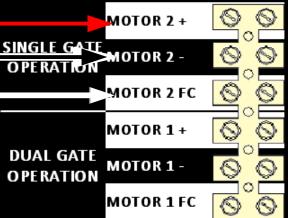
## **BFT PHOBOS BT AND IGEA BT GATE OPERATORS ONLY**

For single gate operation, connect motor leads to MOTOR 2 terminals.

Second motor must be connected to MOTOR 1

On a dual gate application, MOTOR 2 will start to open before MOTOR 1. In turn, MOTOR 1 will start to close before MOTOR 2

### **MOTOR CONNECTIONS**

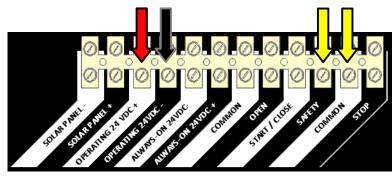


### PHOTOBEAM SENSOR CONNECTION

Photo-beam sensors should only be used as safety devices, not as free exit devices.

Sensors must be powered from **OPERATING 24VDC** output

Remove installed jumper. Connect the normally closed contacts to terminals SAFETY and COMMON.



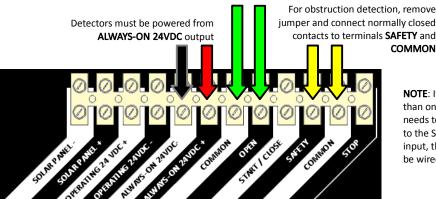
NOTE: If more than one device needs to be wired to the Safety input, they must be wired in series

#### For free exit application, connect the normally open contacts to terminals **COMMON** and **OPEN**

## For obstruction detection, remove

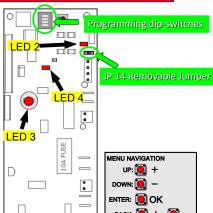
LOOP DETECTOR CONNECTIONS

COMMON



NOTE: If more than one device needs to be wired to the Safety input, they must be wired in series

### SYSTEM PROGRAMMING



#### LED2 – Libra programming jumper (JP14)on

LED3 - (1 flash/sec) Programming receiver channel 1

(2 flashes/sec) Programming receiver channel 2

(Steady) Hidden button programmed

(3 flashes) Low battery

LED4 - Charging batteries

#### **ECOSOL PROGRAMMING**

Dip-switch Settings

**LED LEGEND** 

•Switch 1 – Turn on for secondary batteries connection

•Switch 2 – Enables Quick Radio Programming

•Switch 3 – Command relay delay (MUST BE TURNED ON)

•Switch 4 - Command relay delay

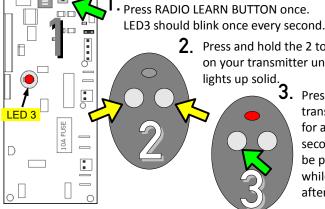
#### LIBRA LIL-R PROGRAMMING

Jumper must be installed over both pins on JP14 on the ECOSOL interface board during Libra UL-R programming. Jumper MUST BE REMOVED after

#### Press th OK button twice to enter programming.

Use the UP (+) and DOWN (-) buttons to navigate the menu. Use the ENTER (OK) button to enter a programming menu area. Use the UP & DOWN button simultaneously to navigate back within the menu and/or exit programming.

#### **REMOTE CONTROL PROGRAMMING**

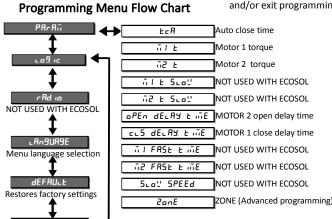


2. Press and hold the 2 top buttons on your transmitter until LED3

lights up solid.

3. Press the desired button on the transmitter. LED3 should blink rapidly for a second a goes back to a blink per second. If additional transmitter are to be programmed, repeat steps 2 and 3 while LED3 is blinking. System times out after 10 seconds

Automatic torque setting



Auto close enable START ignored on opening ibi oPEn FRSt cLS Anti-tailgate Photoc\_ oPEn Safety input ignored on opening LESE Phata NOT USED WITH ECOSOL Single motor operation bioc PEr5 15t Pre-open push SEArt にゅうを START input as CLOSE only F 'HE' COGOL NOT USED WITH ECOSOL r 引d io Pro9 NOT USED WITH ECOSOL Master / Slave designation

Technical Support: 877-995-8155